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9 The prediction of bending strengths in SFRSCC using 10 computational fluid dynamics (CFD) 11 12 13

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22 Abstract 23

24 This research establishes a correlation between the predicted fiber orienta-
25 tion in Steel Fiber Reinforced Concrete (SFRC) and the flexural behavior
26 of the composite material. It is well known that the proper alignment of
27 fibers in the direction of tensile force enhances the mechanical properties
28 of concrete. As recent studies have corroborated, the flow induced by self-
29 compacting properties can influence fiber orientation. Thus, both technolo-
30 gies may be combined in the casting of a real-scale Steel Fiber Reinforced
31 Self-Compacting Concrete (SFRSCC) wall (3-meters high, 6-meters long and
32 0.15-meter thick). Computational Fluid Dynamics (CFD) methods are ap-
33 plied, implementing a Bingham plastic model in a homogeneous fluid, in order
34 to predict fiber orientation. The acceptability of the expected orientations
35 is confirmed by analyzing the velocity fields of the fluid throughout succes-
36 sive time-steps of the simulation and by linking those fields to the bending
37 strengths (pre- and post-cracking) of prismatic specimens extracted from the
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9 wall. Expected orientations are further supported by non-destructive mag-
10 netic methods. Prediction techniques are of paramount importance nowa-
11 days, because design rules are only based on the response of preliminary
12 prismatic specimens that are not representative of the final real structural
13 elements. This novel methodology characterizes the material through the
14 analysis of numerical simulations, without the cost of casting real elements,
15 which notably simplifies the assessment of materials for use in new structural
16 elements and geometries.
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24 *Keywords:*

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26 CFD, SCC, fiber orientation, strength prediction, SFRC
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28 29 **1. Introduction**

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32 Several research projects have sought to simulate material flow using var-
33 ious computational tools. More complex configurations are required for sim-
34 ulations of heterogeneous concrete matrices. In the case of Steel Fiber Rein-
35 forced Concrete (SFRC), the reinforcement is accomplished by short, discrete
36 and randomly distributed steel fibers. The inherent difficulty of predicting
37 and assessing fiber orientation in hardened concrete is the main drawback to
38 its wider use. These fibers increase the tensile strength, ductility and crack-
39 bridging capability of the composite at the expense of workability. Also, an
40 incorrect mix-design can lead to inappropriate behavior such as fiber balling,
41 blocking and segregation. The slender fiber shape requires more paste to
42 avoid these sorts of disadvantages. Self-Compacting Concrete (SCC), which
43 also improves performance, can be merged with the former technology to
44 produce what is known as Steel Fiber Reinforced Self-Compacting Concrete
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9 (SFRSCC). This synergy allows the application of computational techniques
10 that simulate the composite material as a fluid. Some researchers [1] [2] have
11 demonstrated how the tailored fresh state performance of concrete can force
12 the fibers to align in the direction of the flow, achieving planar and, even
13 more remarkably, unidirectional orientations.
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19 *1.1. Prediction*

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22 Computational tools have the potential to reduce uncertainty. Several
23 currents of research seek to achieve that goal, such as research into homo-
24 geneous fluid, discrete particles, and particles suspended in a medium; each
25 with its own advantages and disadvantages [3]. Those lines of research re-
26 port tests for small movements by using, for example, the slump flow test,
27 although only very few have tested large structural elements. [4] were the first
28 to simulate the flow of concrete, on the assumption that concrete behaves
29 in a similar way to a homogeneous fluid. They developed the Viscoplas-
30 tic Finite Element Method (VFEM) and the Divided Viscoplastic Element
31 Methods (DVEM) for 2D flow. The free surface corresponds to the mesh
32 deformation, in the first case, and to the displacement of virtual markers,
33 in the second case. However, the Volume Of Fluid (VOF) method, adopted
34 by [5] for simulating SCC casting, is the most extensively used. Slight dif-
35 ferences when analyzing complex materials are offset by its simplicity and
36 reduced computational cost. [6] established the Distinct Element Methods
37 (DEM) that led to SCC flow modeling, splitting the coarse aggregate and the
38 mortar phase [7]. Moreover, Dissipative Particle Dynamics (DPD), a meso-
39 scopic simulation technique, has been used for simulating SCC rheology [8].
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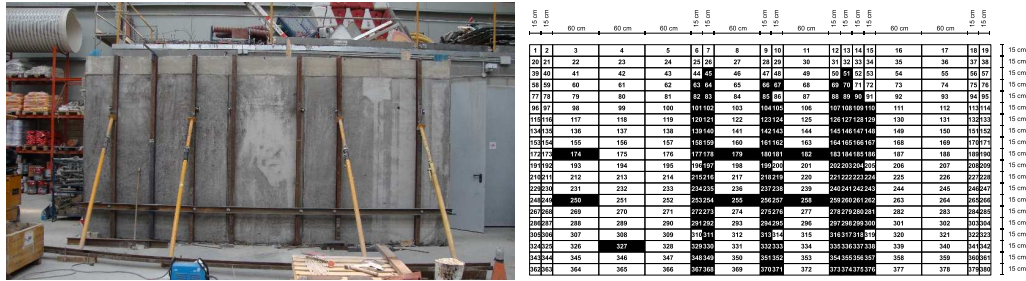
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9 materials better than others and is more appropriate for a vibrated concrete,
10 where the larger amount of granular particles determines the behavior of the
11 concrete. The aggregates are coarser and are used in larger amounts than
12 in an SCC. Nevertheless, several studies point to its suitability to simulate
13 the flow of SCC. However, the parameters that are needed have no physical
14 meaning. As the real behavior of SFRSCC resembles small size aggregates
15 in a mortar paste, another alternative line of investigation is the simulation
16 of particles suspended in a viscous medium. Those particles could also be
17 the fibers themselves, so that their distribution and orientation could be ob-
18 tained. [9] modeled aggregates as spherical particles suspended in a mortar
19 phase, for simulating concrete flow that led to the Viscoplastic Suspended
20 Element Method (VSEM). The studies of [10] are based on the FEMLIP
21 method [11], integrating Lagrangian particles in an Eulerian mesh to simu-
22 late different types of concrete (normal, self-compacting, high strength) using
23 the Bingham model. With regard to the use of fibers, [12] determined differ-
24 ences in fiber orientation using the slump test for Newtonian fluids and the
25 Herschel-Bulkley model, with an Eulerian description and a modification of
26 the Level Set Method (LSM). On the other hand, [13] adopted another way
27 of implementing the Lattice-Boltzman model (LBM) instead of solving the
28 Navier-Stokes equations. A modification of the Immersed Boundary Method
29 (IBM) is used as an alternative to the VOF and the LSM methods. Despite
30 their suitability, these methods are not sufficiently mature yet and need fur-
31 ther development [14]. The influence of fiber orientation on the mechanical
32 response is paramount. Based on CFD simulations, a predicted orientation
33 can be obtained in the design stage. The consequent mechanical behavior
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9 that is expected must be corroborated after casting, by a reliable quality control
10 technique. This work is necessary to ensure the previously established
11 safety coefficients. The methods summarized below, are under development
12 for implementation in large structural elements as well as in test specimens.
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17 *1.2. Control*

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19 Among the recently developed non-destructive tests (NDT), the most direct
20 appear to be manual counting of fibers on cut faces and the application
21 of stereological principles (Dupont and Vandewalle 2005), although these are
22 not sufficiently practical. The correlation of electrical [15] [16] [17], magnetic
23 [18] and signal attenuation [19] properties of the material are more suitable
24 for indirectly assessing fiber orientation and distribution. Among those techniques
25 is the measurement of the inductance variation of a given magnetic field,
26 which is due to the inserted ferromagnetic fibers. Note that concrete
27 has no influence on the magnetic field, so the measured range depends only
28 on fiber type, amount and orientation. This paper presents a case study of
29 the casting of a large SFRSCC wall, to examine the agreement between the
30 expected and the real fiber orientations. Simulations of Computational Fluid
31 Dynamics (CFD) were performed for this prediction, while magnetic methods
32 determined the actual amount of fibers and the orientation. In parallel,
33 aspects regarding the fiber suitability, mix-design, casting processes, testing
34 methods (NDT or otherwise) and mechanical properties were also analyzed.
35 According to this novel method, a remarkable link is established, by merging
36 data, fiber orientation and residual strength, that makes it possible to predict
37 the tensile response of the material before performing any mechanical tests.
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39 The results reported in this paper form part of a wider research project that
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(a) Cast wall (b) Cut scheme

Figure 1: Analyzed structure and cut scheme of specimens.

is focused on the industrial applications of the material. The suitability of new structural elements and geometries can be checked in an economic way, boosting wider use of fibers in cementitious composites.

2. Case study

The use of real rather than laboratory-scale specimens is considered necessary, in order to work with sufficiently representative concrete movements. Hence, a real-scale 3-meter high, 6-meter long and 0.15-meter thick, SFRSCC wall was cast in situ [2]. The casting process involved pumping in the concrete from a lower corner until it had filled up the formwork. The thickness was selected based on the standardized dimension of specimens for the following tests to be performed: compression, shear, double punching, bending, permeability and magnetic tests. For that purpose, 380 prismatic (150x150x600 mm) and cubic (150x150x150 cm) specimens were cut from the wall, according to Figure 1. Their components and mix-design were adequately selected to satisfy key points relating to self-compactability, strength and durability.

3. Materials

Hooked-end fibers were selected from among the several fiber types found on the market, as the hook provides the necessary anchorage in the concrete matrix, transferring tensile stress, in the case of cracking. As the workability of the mass is reduced by increasing their amount, length and diameter, the fibers should be selected to achieve the best performance in both the fresh and the hardened states. Short lengths are more susceptible to slip from the matrix, but large ones make a robust and self-compacting mix-design complicated. Therefore, after suitable pull-out tests on individual fibers to verify the two preceding points, intermediate length fibers were chosen. The length and diameter of the selected fibers (HE 1/50) were 50 mm and 1 mm, respectively. The mixing procedure created a thick mixture. using an acceptable mix design based on previous experience. The proportions shown in Table 1 were determined, by taking 350 kg/m^3 of cement as a minimum content, in view of possible chemical attack by highly aggressive substances [20], and 0.45 as the respective maximum water/cement ratio. Even though the cement amount could be considered high, exposure to aggressive substances can be a reason to increase the minimum content. A compact granular skeleton is necessary to obtain acceptable performance (durability and strength). So, slender fibers are taken as new aggregates with a higher specific surface, which requires more mortar paste for lubrication purposes and to obtain a workable SCC. As they also interfere with the free positioning of the aggregates, it is important to search for the proportions which lead to a lower porosity. There is no one method to predict the rheological behavior of the mix and a series of characterization tests are required. In this research,

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Cement	Sand	Gravel	Plasticizer	Superplast.	Steel	Water
(kg/m ³)	(kg/m ³)	(kg/m ³)	(% weight of cement)	(% weight of cement)	fibres (kg/m ³)	(l/m ³)
434	1141	626	1.02	1.16	50	178

Table 1: Mix-design for the Steel Fiber Reinforced Self-Compacting Concrete (SFRSCC).

V-funnel and slump flow tests were performed to optimize the admixture amounts. A new generation of polycarboxylate ether-based superplasticizers (PCEs) was employed as high range water reducers. The final batch, prepared in the plant, showed a final spread of 710 mm (D_f) and needed 1.9 s to reach the 500 mm diameter line (T_{50}).

3.1. Flow models

In this study a homogeneous single-fluid approach was adopted. Concrete motion was determined by solving the Navier-Stokes equations at a constant viscosity, as shown in Equation (1), with the open-source Gerris flow solver [21]. Where an incompressible fluid is considered, mass conservation must be guaranteed, according to Equation (2).

$$\rho \left(\frac{\partial u}{\partial t} + u \nabla u \right) = -\nabla p + \nabla(2\eta|\gamma|) + \rho g \quad (1)$$

$$\nabla \cdot u = 0 \quad (2)$$

The Volume Of Fluid (VOF) technique is applied to track the free surface, which involves an adaptive mesh refinement, so that this gradient between

concrete and air is simulated. The method provides accurate adaptation to changes in topology. Depending on the values of the injected tracer, both phases can be distinguished. Each volume fraction presents properties related to the tracer values, as indicated in Equation (3a) to (3c). Tracer c adopts values from 0 to 1, for air and concrete, respectively. Intermediate values show the interface or gradient of the control volume.

$$\rho = \rho_c \cdot c + \rho_a \cdot (1 - c) \quad (3a)$$

$$\mu = \mu_c \cdot c + \mu_a \cdot (1 - c) \quad (3b)$$

$$\tau_0 = \tau_{0,c} \cdot c + \tau_{0,a} \cdot (1 - c) \quad (3c)$$

Fluid movements were simulated by assuming Bingham plastic behavior (Figure 2). Apparent viscosity is a basic input parameter, based on yield stress (τ_0) and plastic viscosity (μ). These values can be obtained with a rheometer, although [22] demonstrated that different devices show a range of different measured values. Another method involves the analysis of the slump flow test results: the final spread (D_f) and the time taken to pass over the 500 mm diameter circle (T_{50}). Yield stress is related to the maximum diameter the concrete will reach during the test, while viscosity mainly refers to the speed at which it flows. SCC shows a lower yield stress value than vibrated concrete, due to its low resistance to flow, but its viscosity is higher as it contains more fine aggregates than vibrated concrete.

Several slump flow tests were simulated in Gerris and compared with real slump tests and rheometer measurements [23]. The correlations made it possible to establish the input data (τ_0 and μ) needed for the proposed

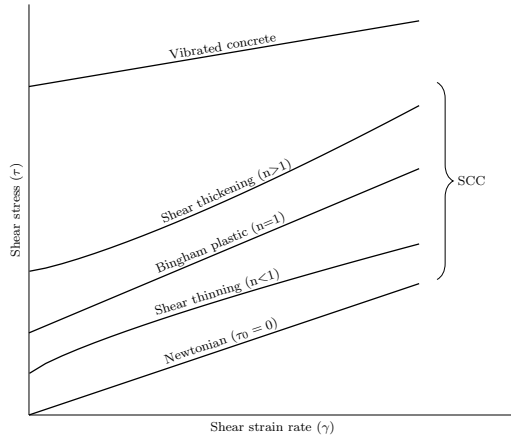


Figure 2: Rheological models.

mix-design. Unlike studies done to date, the inclusion of a slump flow test with a solid lifting cone in these simulations was notable. The mass only flows through the gap at the bottom, which increases as the cone is lifted upward, retaining any horizontal movements at the top of the slump. The parameters of the Bingham model were established from those simulations, in which the slump flow test was performed on the concrete pumped into the formwork. The final diameter (D_f) reached by the mass and the time it needed to arrive at a 500 mm diameter (T_{50}) were 710 mm and 1.9 s respectively. Those correlations suggest that the concrete should be simulated as a Newtonian fluid, rather than a Bingham plastic, with a null yield stress ($\tau_0 = 0$ Pa) and moderate viscosity ($\mu = 63$ Pas). Some authors [24] have argued that the Bingham plastic model is not the most appropriate with which to model concrete behavior. The reason for this assertion is because it gives negative yield stress values for large slumps, which is physically impossible. Hence, the preference for a Newtonian model in this study. Even though the

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9 Bingham model underestimates shear stress, other models such as Herschel-
10 Bulkley (shear thickening) overestimate the yield stress. In this research, the
11 Bingham model is preferred, because its parameters have physical meaning
12 and are easier to determine than those of the Herschel-Bulkley model.
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17 *3.2. Simulation set-up*

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20 A complete model of the cast wall is represented in Figure 3, in which the
21 main analysis centers on the 0.15 meter side boxes. These boxes are divided
22 into 800 study units in accordance with the dimensions of the wall (length,
23 height and thickness), although some of them are occupied by the pumping
24 pipe. Solids are included to simulate the clamps arranged to tie both sides
25 of the formwork, so as to consider the flow alteration that they might cause
26 in the simulation. The concrete is pumped in at the lower left corner of the
27 formwork through a pipe and flows from left to right and from bottom to
28 top as the formwork fills up. The upper face is left open so that the air can
29 escape without entrapment within the concrete.
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39 The model implements a dynamic mesh refinement, focused on the in-
40 terface and the areas of high vorticity. This adaptive refinement promotes
41 a better approach while reducing the computational cost, providing relevant
42 information at selected points. These application criteria are then compared
43 with the results of the magnetic method, for which 0.15 cm side cubic spec-
44 imens were used. Therefore, the study boxes have the same dimension and
45 are only refined up for to 3 levels, when the concrete gradient passes through
46 them or the vorticity inside is noteworthy. Figure 4 shows the basic study
47 unit referred to as a box and its different refinement types and levels. Ge-
48 ometrical discontinuities, such as clamps between lateral formworks, require
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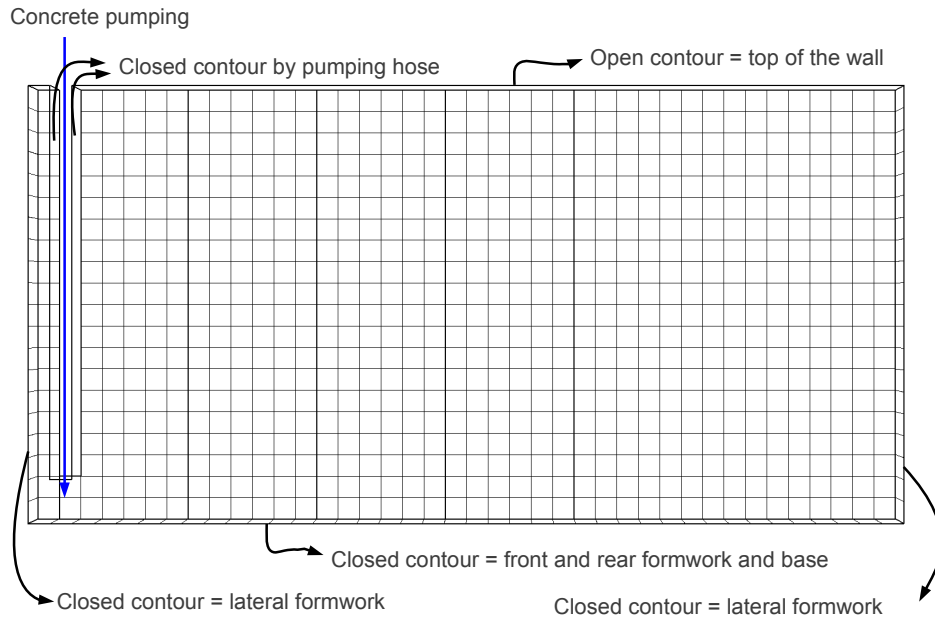


Figure 3: Simulation model and boundary conditions.

static refinement throughout the simulation, to accommodate the mesh to such small holes. On the other hand, the refinement is also dynamically performed in some areas which need a closer approach, coarsening it later where the flow is stabilized. Parallel computing with multiple processors is used, which reduces the computational cost. As a result, the position of the tracer, pressure and velocity fields of the two phases during the entire casting process were obtained for all the boxes at each time step. Since the study focuses on movement of the fresh concrete, the results of the gaseous phase are omitted. Although the procedure and the results were initially different, the simulation was adapted to the specific case under analysis. There was still a slight difference between the casting process of the wall and its simulation, as the removal of the pumping equipment was not reflected in

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9 the latter. Pipe extraction would trigger a certain movement of the mass,
10 especially in a vertical direction, that could change the local orientation of
11 the fibers in the vicinity of the discharge point. However, as this was not
12 considered very relevant for the mechanical behavior of the whole wall, it was
13 decided to limit the simulation to the concrete pumping process. The simu-
14 lation was performed in a manner that was consistent with the actual casting
15 process, with the pumping pipe at the bottom of the formwork throughout
16 the operation. This was not, however, the same as the previously established
17 procedure, which determined a rate of ascent up the pipe as the concrete-air
18 interface rose upwards. Nevertheless, casting procedures that were as real
19 as possible were maintained in this study, as otherwise, the communication
20 between agents is usually not as effective as expected. Consequently, the test
21 replicated the conditions of placing concrete. The pumping rate was estab-
22 lished, based on the time needed to complete the casting process. It took 8
23 minutes to fill the formwork with a volume of 2.7 m³, equivalent to a flow
24 rate of 0.3375 m³/min. No-slip conditions were applied to the boundaries,
25 therefore the reduced flow speed of the concrete in contact with the formwork
26 was not considered.

4. Validation of expected orientations

47 Two velocity trends may be remarked upon during the simulation process.
48 At the start, the unimpeded flow of concrete along the whole length and,
49 as the volume of pumped concrete increased, boundary conditions slowed
50 down the mass that was located furthest away from the pumping point. The
51 restructuring of the matrix, due to the common thixotropic behavior of SCC,
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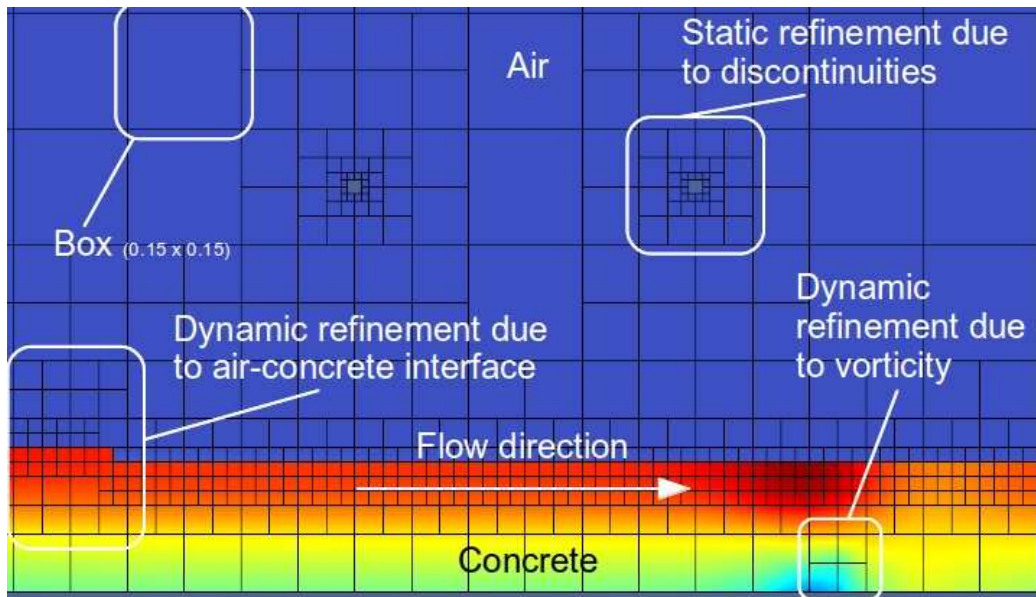


Figure 4: Refinement criteria and levels.

increased its shear strength. Therefore, the freshly pumped concrete did not have enough energy to displace the concrete that had previously been poured and to modify the trend, rising to the upper levels, as shown in Figure 5. The vertical component of the velocity vector in the proximity of the pumping pipe to the detriment of the horizontal vector is notable. The trend was reversed as the distance from the point of discharge increased and as the flow therefore stabilized. However, the higher the level where the box was located, the greater the vertical/horizontal component ratio. All the velocity fields can be analyzed for each individual box throughout the whole simulation. The tracer parameters were saved for each box at each time step. Figure 6 shows the progression of both velocity components in boxes # 85 and # 294 during the simulation. The figures focus on the time range within which the data were obtained, hence, the X-axis is discontinuous and different for each

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9 specimen. A sketch of the position of each specimen is also provided in both
10 cases. The horizontal velocity predominated in the lower boxes, although
11 it tended to decrease rapidly throughout the simulation. Both components
12 were more similar in the upper boxes and continued their displacement until
13 the end of the pumping process. The concrete phase took longer to reach
14 those boxes, presenting a shorter impact in the simulation than the lower
15 ones.
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22 These behaviors can be illustrated as an average orientation based on
23 velocity component ratios. Thus, it is possible to compare simulation results
24 with real orientation detected by NDT methods. Hereafter, the longitudinal
25 direction of the wall or the X-axis is taken as the origin of the defined an-
26 gles. Among the control techniques available, the most interesting one is the
27 magnetic method. Its simplicity and the repeatability and reliability of the
28 measurements taken have previously been demonstrated [25].
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36 The inductance of any magnetic field is altered when a ferromagnetic ma-
37 terial is introduced. Three different coils were built and the proportionality
38 of the measurements, based on their self-inductance, verified. All the cubic
39 specimens, 140 in total, were analyzed along their three axes. Besides, 7
40 prismatic specimens were cut into four quarters, obtaining a further 28 cu-
41 bic specimens, to which magnetic methods were applied. The orientation of
42 each axis was determined by the inductance variation value in that direc-
43 tion. The average of the three axes was related to the fiber amount in the
44 specimen. The X-axis corresponds to the length of the wall, while the Z-axis
45 corresponds to its height. The thickness or transversal direction of the wall
46 is denoted on the Y-axis, but as expected, fewer fibers are detected along
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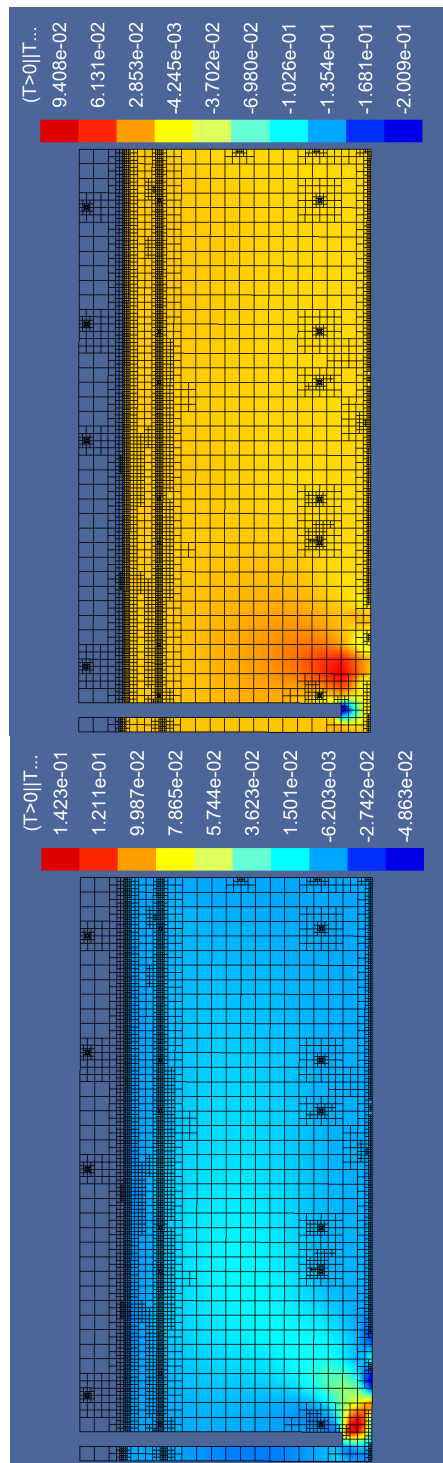
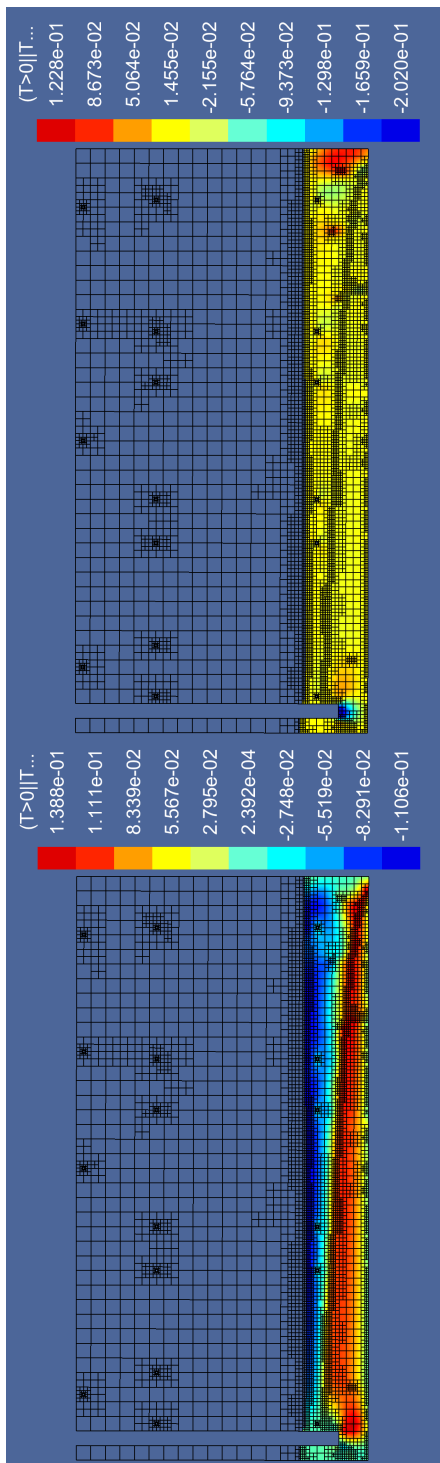


Figure 5: Horizontal (left) and vertical (right) velocity fields, for initial (upper) and final (lower) time steps.

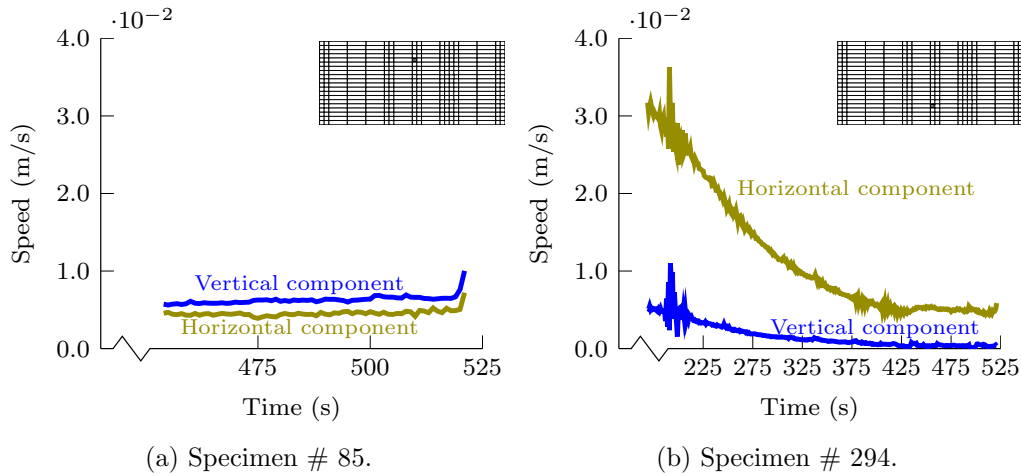


Figure 6: Progress of velocity fields for specimens # 85 and # 294.

that direction and they present fewer variations. Having such a thin wall prevents the mass from spatial flow, resulting in a two-dimensional flow as that adopted for the simulation. Figure 7 shows a superposition of both data sets for the available specimens: those from the 2D simulation and the NDT testing. With the exception of some specimens, most of them show similar behavior as expected. Note that cubic specimens are mainly analyzed, because the set-up for the magnetic method fits the cubic ones best. Prismatic specimens can only be measured on the X-axis after they have been cut into quarters. A total of 7 specimens were prepared and those from both sides were discarded, because a water-stop strip was attached to them and some nails arranged for fixing the wooden formwork altered the measurements. A slight segregation of fibers also occurred at the top due to some priming water in the pump, which meant that those specimens were also neglected.

The lower side presented expected orientations, mainly on the X-axis,

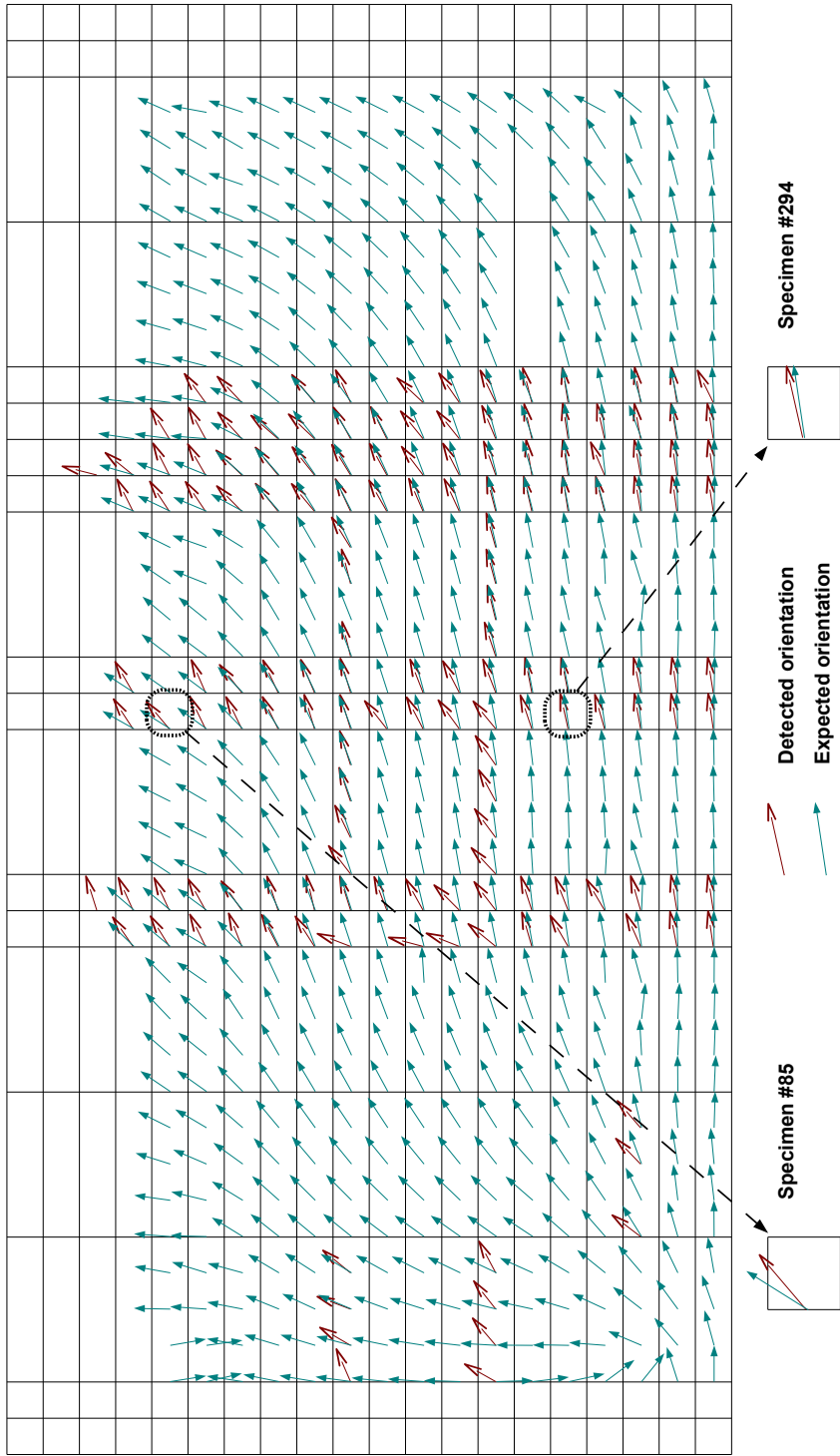


Figure 7: Superposition of predicted orientations and detected ones.

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9 while the upper sides tended to show a more influential vertical velocity com-
10 ponent. This agrees with previous statements. Intermediate heights exhibit
11 variable orientations depending of the distance from the pumping pipe and
12 their proximity to the lateral formwork, which restrains the horizontal flow
13 of the mass (Figure 7). The distribution of fiber orientations throughout the
14 height and the length of the wall was remarkable, as shown in Figure 8. The
15 lower and upper parts have similar orientations throughout the wall, while
16 intermediate rows show an uneven alignment depending on the horizontal
17 position of the studied specimen. The reason for this uneven alignment is
18 the transitional zone created by the vertical flow of the mass near the pump-
19 ing pipe and the field of horizontal velocity in the stabilized area furthest
20 away from the pipe. The standard deviation of the curves faithfully reflects
21 those differences. These values vary between 12-13% for the lower and the
22 upper rows to 32% for those in the middle.
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37 **5. Strength prediction**

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40 The orientation of fibers around crack planes, influences the crack-bridging
41 potential of the material. Higher amounts of fibers aligned with the tensile
42 direction will achieve higher strength values. Magnetic methods have already
43 been used to verify mechanical properties of hardened SFRSCC specimens
44 [2] as a control quality method. This study takes a step forward, predict-
45 ing through the simulations the flexural response of the material. Starting
46 from the bottom of the wall, prismatic specimens from one of every two rows
47 have been tested according to the three-point bending test (UNE-EN 14.651).
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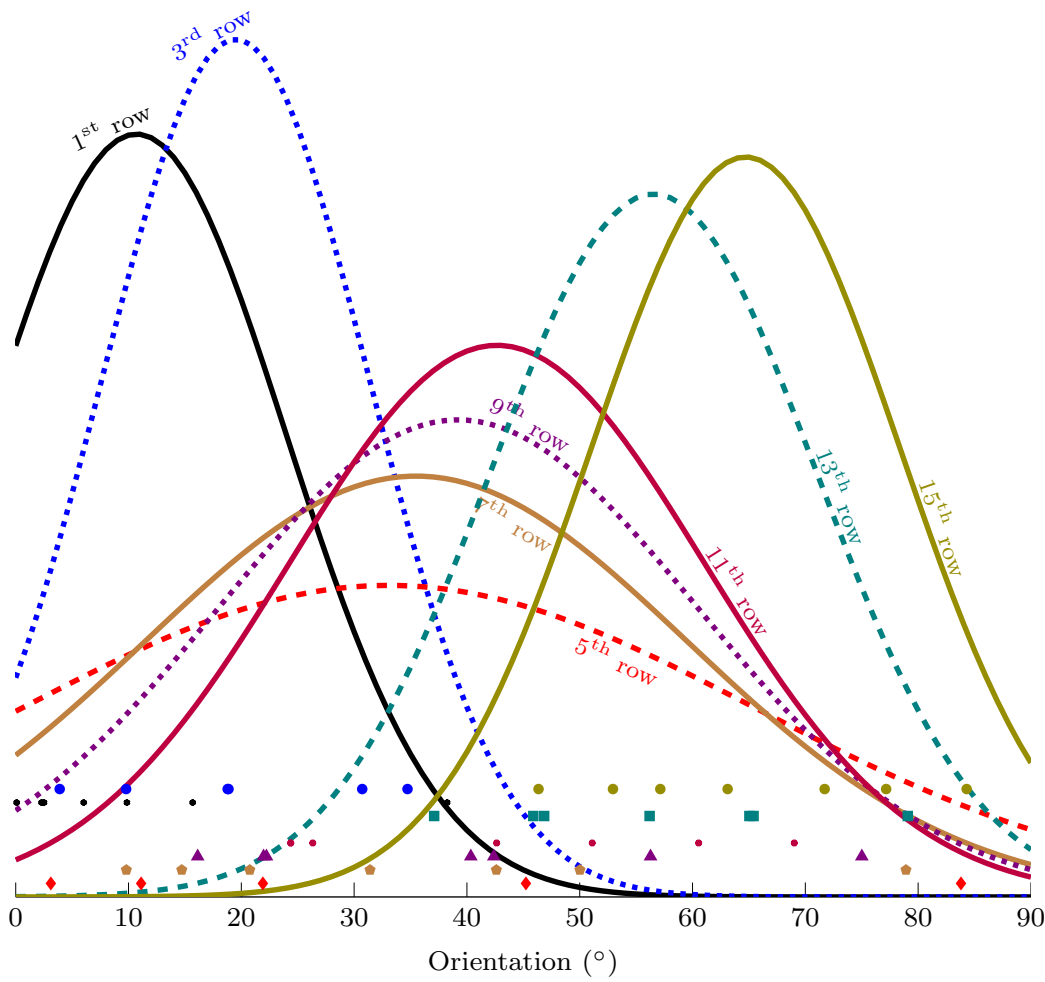


Figure 8: Gaussian distribution of orientations.

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 9 points of the lower face, while the load was applied in the center of their up-
 10 per face. Tensile force developed along the longitudinal direction of the wall
 11 or its X-axis. Flexural tensile strength was measured by determining the
 12 Limit Of Proportionality (LOP) and successive residual strengths. These
 13 strengths correspond to the forces applied to obtain diverse Crack Mouth
 14 Opening Displacements (CMOD) of the notch and are the key parameters
 15 to define constitutive laws for the material, although the procedure differs
 16 between the various standards. Figure 9 illustrates the relation between fiber
 17 orientation and strength. As expected [26] [27] obtuse angles denote almost
 18 horizontal orientations providing high strength values, whereas acute angles
 19 provoke a rather brittle failure. Furthermore, it is clearly shown that the
 20 maximum values are reached for angles slightly above the horizontal plane,
 21 as [28] proven by the pull-out test on individual fibers. Matrix spalling and
 22 fiber straightening [29] increase those values. The bending test presents an
 23 inherent scatter in measured values, the variation coefficient of which can
 24 often exceed 20% [30], although it is recognized that those values decrease
 25 for larger elements. Besides, the notch required by the standard and made
 26 in the center of the lower face, cuts an unequal number of fibers in each
 27 specimen, increasing the dispersion.
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$$y = A_b \cdot \frac{A_t - A_b}{\left(1 + \exp\left(\frac{x-x_0}{w}\right)\right)} \quad (4)$$

However, a trend line (Figures 9a to 9d) can be approximated through
 a sigmoid function expressed in Equation (4). The Levenberg-Marquardt
 algorithm (LMA) for non-linear curve fitting was applied, due to the scatter
 in the plotted data. This iterative procedure minimizes the square of the

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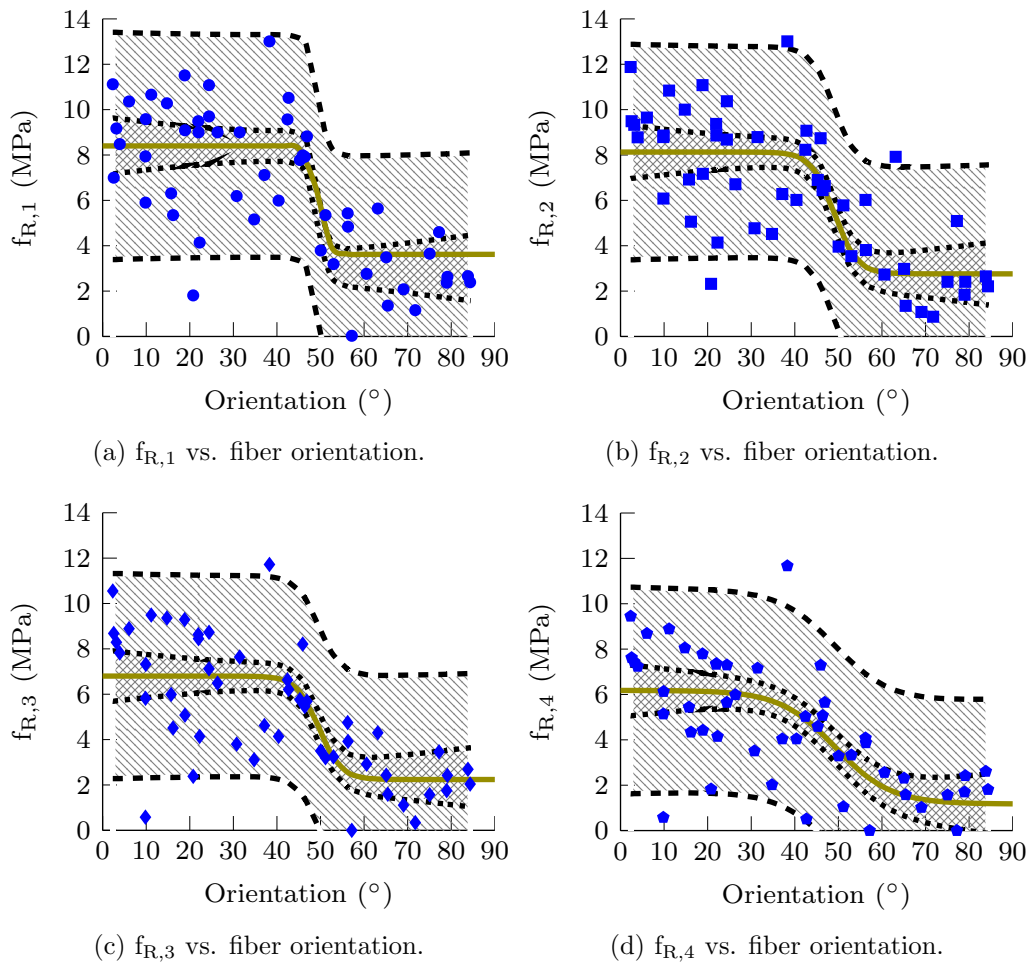


Figure 9: Prediction of residual strengths based on orientation.

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9 deviations with the least squares method. The reliability of the defined
10 trend line is assessed through a confidence interval, defined by two dotted
11 lines demarcating a lined grid. The narrow confidence interval denotes a
12 reasonably well fitted trend line. Furthermore, the dashed lines furthest from
13 the trend line establish an area shown by oblique hatching, that requires
14 further study. The inherent scatter in the bending test together with the
15 results of fiber segregation offer a wide area for future study. Nonetheless,
16 the link between residual strength and fiber orientation is quite remarkable.
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24 The physical meaning of the parameters adopted for the equation, show
25 useful information for understanding the behavior of the material. Its values
26 also fit the terms of the model. A_b and A_t are the respective asymptotes for
27 the function that limit the minimum and maximum values to be reached. It
28 should be noted that this conservative approach excludes the slight increase
29 for low inclination angles. The values x_0 and w correspond both to the
30 inflexion point and to the width of the transition zone from exponential
31 growth to its deceleration and change the curvature of the function. Two
32 distinct behaviors are separated by that imaginary border of the transition
33 zone. Orientation with inclination angles lower than 50 degrees show an
34 appropriate strength level, while those remarkably out of the tensile direction
35 present lower values. The change is more abrupt for initial residual strengths,
36 since the bearing capacity of highly inclined fibers is effective at higher crack
37 openings. This approach is very interesting as one continuously differentiable
38 function is sufficient to describe the strength of the material at different stages
39 (pre- and post cracking) for any orientation. Table 2, summarizes the input
40 data necessary to adopt the function in each case.
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Key parameter	A_b (MPa)	A_t (MPa)	x_0 ($^\circ$)	w ($^\circ$)
$f_{R,1}$	3.02	8.40	49.42	1.19
$f_{R,2}$	2.76	8.13	49.02	2.61
$f_{R,3}$	2.24	6.80	49.50	2.55
$f_{R,4}$	1.17	6.18	49.28	6.37

Table 2: Input parameters for predictive sigmoid function.

5.1. Constitutive law

From the residual strengths obtained in the previous section, a $\sigma - \epsilon$ law can be predicted for the material. The procedure follows a four exponential approach [31] and will be compared with the diagrams plotted according the EHE-08 for the same specimens. The maximum strength reached in the pre-cracking stage is obtained as the characteristic tensile strength according to Model Code 2010. On the other hand, the tail of the curve of the diagram differs depending on the reinforcement level. The strength term governing the shape of the tail of the curve is determined according to the first residual strength of the post-cracking stage. As Figure 9a illustrates, specimens with a high angle degree present low residual strength values and those better aligned with the tensile force, higher values. Table 3 summarizes all the key parameters needed to define the behavior in both cases. Note that specimens located in the transition zone (Figure 9) are less likely to fit to the multilinear diagram.

As Figure 10 shows, the exponential approach lies usually below the established behavior defined by the destructive tests and the concrete code.

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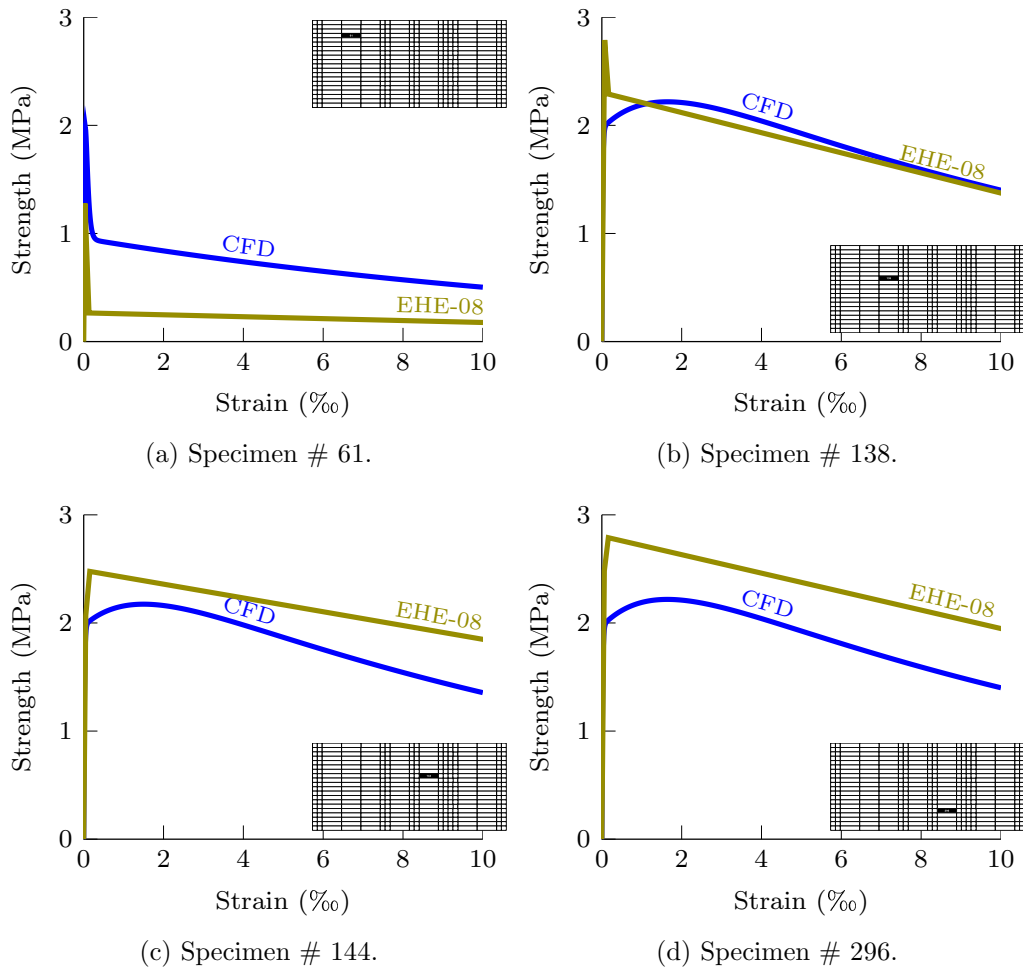


Figure 10: Multilinear diagram [20] and exponential approach.

Stage	f_{pre}	x_{pre}	α_{pre}
Pre-cracking	Fiber angle $> w$ ($^\circ$)	$f_{ct,L}^f = 0.21 \sqrt{f_{ck}^2}$	0.01
	Fiber angle $< w$ ($^\circ$)		100
		0.005	1.001
	f_{post}	x_{post}	α_{post}
Post-cracking	$f_{R,1}$ (Fig. 9a)	0.5	10

Table 3: Kay parameters for the predicting four exponential model.

Therefore, the prediction can be considered conservative. As an exception, specimen # 61 shows a rather low strength level than what was expected. It is not due to an inaccurate estimation of the lower asymptotic limit, but to a static and dynamic segregation that occurred on the upper side of the wall. Specimens located in that area present a similar behavior. The Fiber Dynamic Segregation Index (FDSI) [32] obtained in this case, has been already analyzed [33]. The single fluid model considers an uniform fiber distribution and, therefore, reinforcement of the matrix. Even though segregation is not detected and it does not fit the exact values, the high angle that fibers present with respect to the horizontal axis, denotes the abrupt drop after matrix cracking and the consequent low residual strengths. The slight discrepancies also have their origin in the inherent scatter of the aforementioned bending test and the criteria adopted by the diverse standards, in this cases the UNE-EN 14.651, to determine the LOP and the residual strengths.

Therefore, this method allows to predict the mechanical properties of the SFRSCC, regarding its tensile behavior, and detects weak points in the structure. All this information can be obtained without having cast the

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concrete and subjected it to destructive testing, providing significant time and cost savings.

6. Conclusions

A methodology for predicting the mechanical properties of fiber reinforced concretes under bending tests has been presented in this study. The acceptability of Computational Fluid Dynamics (CFD) has been demonstrated for simulating the flow of SFRSCC. The single homogeneous fluid approach along with the Volume of Fluid (VOF) method resulted in accurate fiber orientation prediction, at reduced computational costs. Therefore, this technique is considered capable of detecting incorrect casting procedures and weak points within the structure, prior to its actual construction. Likewise, unsuitable concrete rheologies can be ascertained from the formwork geometries that have been designed. The research has focused on a real-scale structural element, rather than a laboratory scale specimen. The motion of the mass was therefore uncertain, invalidating possible conjectures. Adoption of the proposed trend lines as calibration patterns has provided interesting design tools with which to determine the key parameters (i.e. residual strengths) established in various standards. From those key parameters and following the procedure of each standard, the constitutive law of the material can be predicted at every point of the structural element. This is essential, as fiber orientation and concrete strength, may vary considerably within the element depending on the mass flow of the concrete. This predictive procedure, allows us to determine structural areas with a inadequate reinforcement level due to incorrect alignment of fibers. Detecting weak points beforehand, increases

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9 the security of the structures while reducing their quality control costs. Also
10 multiple simulations can be performed, without real castings, to establish
11 the best process to apply on site.
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