## CONSTANT MEAN CURVATURE HYPERSURFACES WITH CONSTANT $\delta$ -INVARIANT

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We completely classify constant mean curvature hypersurfaces (CMC) with constant  $\delta$ -invariant in the unit 4-sphere  $S^4$  and in the Euclidean 4-space  $\mathbb{E}^4$ .

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**1. Introduction.** A hypersurface in the unit round sphere  $S^{n+1}$  is called isoparametric if it has constant principal curvatures. It is known from [1] that an isoparametric hypersurface in  $S^4$  is either an open portion of a 3-sphere or an open portion of the product of a circle and a 2-sphere, or an open portion of a tube of constant radius over the Veronese embedding. Because every isoparametric hypersurface in  $S^4$  has constant mean curvature (CMC) and constant scalar curvature, it is interesting to determine all hypersurfaces with CMC and constant scalar curvature. In [2], it was proved that a closed hypersurface with CMC and constant scalar curvature in  $S^4$  is isoparametric. Furthermore, complete hypersurfaces with CMC and constant scalar curvature in  $S^4$  or in  $\mathbb{E}^4$  have been completely classified in [9].

For each Riemannian n-manifold  $M^n$  with  $n \ge 3$ , the first author defined in [3, 4] the Riemannian invariant  $\delta$  on M by

$$\delta(p) = \tau(p) - \inf K(p), \tag{1.1}$$

where  $\tau = \sum_{i < j} K(e_i \wedge e_j)$  is the scalar curvature and  $\inf K$  is the function assigning to each  $p \in M^n$  the infimum of  $K(\pi)$ ,  $\pi$  running over all planes in  $T_pM$ . Although the invariant  $\delta$  and the scalar curvature are both Riemannian scalar invariants, they are very much different in nature.

It is known that the invariant  $\delta$  plays some important roles in recent study of Riemannian manifolds and Riemannian submanifolds (see, e.g., [4, 5, 6, 7, 8, 10, 11, 12, 14, 15, 16]). In particular, it was proved in [3] that for any submanifold of a real space form  $R^m(\epsilon)$  of constant curvature  $\epsilon$ , one has the following general sharp inequality:

$$\delta \le \frac{n^2(n-2)}{2(n-1)}H^2 + \frac{1}{2}(n+1)(n-2)\epsilon,\tag{1.2}$$

where  $H^2$  is the squared mean curvature function and n is the dimension of the submanifold.

Clearly, every isoparametric hypersurface in  $S^4$  or in  $\mathbb{E}^4$  has constant mean curvature and constant  $\delta$ -invariant. So, it is a natural problem to study hypersurfaces in  $S^4$  and  $\mathbb{E}^4$  with CMC and constant  $\delta$ -invariant. The purpose of this paper is thus to classify such hypersurfaces.

Our main results are the following theorems.

**THEOREM 1.1.** A CMC hypersurface in the Euclidean 4-space  $\mathbb{E}^4$  has constant  $\delta$ -invariant if and only if it is one of the following:

- (1) an isoparametric hypersurface;
- (2) a minimal hypersurface with relative nullity greater than or equal to 1;
- (3) an open portion of a hypercylinder  $N \times \mathbb{R}$  over a surface N in  $\mathbb{E}^3$  with CMC and nonpositive Gauss curvature.

**THEOREM 1.2.** A CMC hypersurface M in the unit 4-sphere  $S^4$  has constant  $\delta$ -invariant if and only if one of the following two statements holds:

- (1) *M* is an isoparametric hypersurface;
- (2) there is an open dense subset U of M and a nontotally geodesic isometric minimal immersion  $\phi: B^2 \to S^4$  from a surface  $B^2$  into  $S^4$  such that U is an open subset of  $NB^2 \subset S^4$ , where  $NB^2$  is defined by

$$N_p B^2 = \left\{ \xi \in T_{\phi(p)} S^4 : \left\langle \xi, \xi \right\rangle = 1, \; \left\langle \xi, \phi_* \left( T_p B^2 \right) \right\rangle = 0 \right\}. \tag{1.3}$$

In contrast to [2, 9], we do not make any global assumption on the hypersurfaces in Theorems 1.1 and 1.2.

As an immediate application of Theorem 1.1, we have the following corollary.

**COROLLARY 1.3.** Let M be a complete hypersurface of Euclidean 4-space  $\mathbb{E}^4$ . Then M has constant  $\delta$ -invariant and nonzero CMC if and only if M is one of the following hypersurfaces:

- (1) an ordinary hypersphere;
- (2) a spherical hypercylinder:  $\mathbb{R} \times S^2$ ;
- (3) a hypercylinder over a circle:  $\mathbb{E}^2 \times S^1$ .
- **2. Preliminaries.** Let  $R^m(4)$  denote the complete simply connected space form  $R^4(\epsilon)$  of constant curvature  $\epsilon$ . Let M be a hypersurface of an  $R^4(\epsilon)$ . Denote by  $\nabla$  and  $\tilde{\nabla}$  the Levi-Civita connections of  $M^n$  and  $R^4(\epsilon)$ , respectively. Then the Gauss and Weingarten formulas of  $M^n$  in  $R^4(\epsilon)$  are given, respectively, by

$$\tilde{\nabla}_X Y = \nabla_X Y + h(X, Y), \qquad \tilde{\nabla}_X \xi = -AX$$
 (2.1)

for tangent vector fields X, Y, and unit normal vector field  $\xi$ , where h denotes the second fundamental form and A the shape operator. The second fundamental form and the shape operator are related by

$$\langle AX, Y \rangle = \langle h(X, Y), \xi \rangle.$$
 (2.2)

The mean curvature H of M in  $R^4(\epsilon)$  is defined by  $H = (1/3) \operatorname{trace} A$ . A hypersurface is called a CMC hypersurface if it has CMC.

Denote by R the Riemann curvature tensor of M. Then the *equation of Gauss* is given by

$$R(X,Y;Z,W) = (\langle X,W \rangle \langle Y,Z \rangle - \langle X,Z \rangle \langle Y,W \rangle) \epsilon + \langle h(X,W),h(Y,Z) \rangle - \langle h(X,Z),h(Y,W) \rangle$$
 (2.3)

for vectors X, Y, Z, and W tangent to M. The Codazzi equation is given by

$$(\nabla_X A)Y = (\nabla_Y A)(X). \tag{2.4}$$

Since *A* is a symmetric endomorphism of  $T_pM$ ,  $p \in M$ , we have three eigenvalues a, b, and c with three independent unit eigenvectors  $e_1$ ,  $e_2$ , and  $e_3$  so that

$$Ae_1 = ae_1, Ae_2 = be_2, Ae_3 = ce_3,$$
 (2.5)

where  $A = A_{e_4}$ . The functions a, b, and c are called the principal curvatures and  $e_1$ ,  $e_2$ , and  $e_3$  the principal directions.

With respect to the frame fields  $e_1$ ,  $e_2$ , and  $e_3$  of M chosen above, let  $\omega^1$ ,  $\omega^2$ , and  $\omega^3$  be the field of dual frames and let  $\omega_B^A$ , A, b = 1, 2, 3, 4, be the connection forms associated with  $e_1$ ,  $e_2$ ,  $e_3$ , and  $e_4$ . Then the structure equations of M in  $R^4(\epsilon)$  are given by

$$d\omega^{i} = -\sum_{i=1}^{3} \omega_{j}^{i} \wedge \omega^{j}, \qquad \omega_{j}^{i} + \omega_{i}^{j} = 0, \tag{2.6}$$

$$d\omega_j^i = \sum_{k=1}^3 \omega_k^i \wedge \omega_k^j + \omega_i^4 \wedge \omega_j^4 + \epsilon \omega^i \wedge \omega^j, \tag{2.7}$$

$$d\omega_i^4 = \sum_{j=1}^3 \omega_j^4 \wedge \omega_j^i, \quad i, j = 1, 2, 3.$$
 (2.8)

Moreover, from (2.5), we have

$$\omega_1^4 = a\omega^1, \qquad \omega_2^4 = b\omega^2, \qquad \omega_3^4 = c\omega^3.$$
 (2.9)

Without loss of generality, we may choose  $e_1$ ,  $e_2$ , and  $e_3$  such that  $a \ge b \ge c$ . It is well known that a, b, and c are continuous on M and differentiable on the

open subset  $U = \{p \in M : a(p) > b(p) > c(p)\}$ . The principal directions  $e_1$ ,  $e_2$ , and  $e_3$  can be chosen to be differentiable on U.

Let p be any given point in M. If  $0 > b \ge c$  at p, then, after replacing  $\xi$  by  $-\xi$  and interchanging a and c, we obtain  $a \ge b > 0$  and  $b \ge c$ .

**3. Lemmas.** We follow the notations given in Section 2. Throughout this paper, we will choose  $e_1$ ,  $e_2$ ,  $e_3$ , and  $e_4$  so that  $a \ge b \ge 0$  and  $b \ge c$ .

**LEMMA 3.1.** For each point  $p \in M$ , either

- (a)  $\inf K = bc + \epsilon$  with  $c \ge 0$  at p, or
- (b)  $\inf K = ac + \epsilon \text{ with } c \leq 0 \text{ at } p$ .

**PROOF.** Recall that we have assumed that  $a \ge b \ge 0$  and  $b \ge c$  at p. Let P be any 2-plane in  $T_pM$ . Then P must intersects the 2-plane Span $\{e_1, e_2\}$ . Thus, there exists an orthonormal basis  $\{X, Y\}$  of P such that  $X \in P \cap \text{Span}\{e_1, e_2\}$  and

$$X = \cos \theta e_1 + \sin \theta e_2,$$
  

$$Y = \pm \sin \theta \cos \phi e_1 \mp \cos \theta \cos \phi e_2 + \sin \phi e_3$$
(3.1)

for some  $\theta$  and  $\phi$  with  $\theta \in [0,\pi)$ ,  $\phi \in [0,\pi]$ . It is easy to see that the sectional curvature K(P) of P is given by

$$K(P) = ab\cos^2\phi + c(a\cos^2\theta + b\sin^2\theta)\sin^2\phi + \epsilon. \tag{3.2}$$

We regard the sectional curvature at p as a function  $K(\theta, \phi)$  of  $\theta$  and  $\phi$ . If  $c \ge 0$ , (3.2) can be expressed as

$$K(\theta, \phi) = ac + a(b - c)\cos^2\phi - c(a - b)\sin^2\theta\sin^2\phi + \epsilon,$$
 (3.3)

which implies that  $K(\theta, \phi) \ge bc + \epsilon$  with the equality holding at  $(\theta, \phi) = (\pi/2, \pi/2)$ .

If  $c \le 0$ , we can express (3.2) as

$$K(\theta, \phi) = bc + b(a - c)\cos^2\phi + c(a - b)\cos^2\theta\sin^2\phi + \epsilon,$$
 (3.4)

which implies that  $K(\theta, \phi) \ge ac + \epsilon$  with the equality holding at  $(\theta, \phi) = (0, \pi/2)$ .

**LEMMA 3.2.** On the open subset U on which M has three distinct principal curvatures, the following equations hold:

$$e_2 a = (a - b) \omega_1^2(e_1),$$
 (3.5)

$$e_3 a = (a - c) \omega_1^3(e_1),$$
 (3.6)

$$e_3b = (b-c)\omega_2^3(e_2),$$
 (3.7)

$$e_1b = (b-a)\omega_2^1(e_2),$$
 (3.8)

$$e_1c = (c-a)\omega_3^1(e_3),$$
 (3.9)

$$e_2c = (c-b)\omega_3^2(e_3),$$
 (3.10)

$$(c-b)\omega_3^2(e_1) = (c-a)\omega_3^1(e_2), \tag{3.11}$$

$$(b-c)\omega_2^3(e_1) = (b-a)\omega_2^1(e_3), \tag{3.12}$$

$$(a-b)\omega_1^2(e_3) = (a-c)\omega_1^3(e_2). \tag{3.13}$$

**PROOF.** The proof follows from Codazzi's equation and is a straightforward computation.  $\Box$ 

**4. Proofs of Theorems 1.1 and 1.2.** We use the same notations as before. Let M be a (connected) CMC hypersurface with constant  $\delta$ -invariant in  $R^4(\epsilon)$ . Then the scalar curvature  $\tau$  of M is given by

$$\tau = ab + bc + ac + 3\epsilon. \tag{4.1}$$

From the constancy of the mean curvature, we have

$$a+b+c=r_1\tag{4.2}$$

for some constant  $r_1$ . By combining Lemma 3.1 with (1.1) and (4.1), we obtain

- (i)  $\delta = a(b+c) + 2\epsilon$  with  $c \ge 0$ , or
- (ii)  $\delta = b(a+c) + 2\epsilon$  with  $c \le 0$ .

When  $U = \{p \in M : a(p) > b(p) > c(p)\}$  is empty, M is an isoparametric hypersurface since the mean curvature and the  $\delta$ -invariant are both constant. Thus, from now on, we may assume that U is nonempty and work on U.

We will treat Cases (i) and (ii) on *U* separately.

**CASE** (i)  $(\delta = a(b+c) + 2\epsilon, c \ge 0)$ . Since  $\delta$  is constant, we get  $a(b+c) = r_2 - 2\epsilon$  for some constant  $r_2$ . Combining this with (4.2) yields

$$a = c_1, \qquad b + c = c_2 \tag{4.3}$$

for some constants  $c_1$  and  $c_2$ . For simplicity, let

$$\omega_3^2(e_1) = \mu, \qquad \omega_1^2(e_2) = f, \qquad \omega_2^3(e_2) = g, \qquad \omega_2^3(e_3) = h.$$
 (4.4)

If *b* and *c* are constant, then *M* is isoparametric. So, we assume that *b* and *c* are nonconstant on *U*. Using (4.3), we get  $e_jb = -e_jc$ , j = 1, 2, 3. Thus,

Lemma 3.2 gives

$$\omega_1^3(e_1) = \omega_1^2(e_1) = 0,$$
 (4.5)

$$e_1b = (a-b)f = (c-a)\omega_1^3(e_3),$$
 (4.6)

$$e_2b = (b-c)h,$$
 (4.7)

$$e_3b = (b-c)g.$$
 (4.8)

From (4.5), we know that the integral curves of  $e_1$  are geodesics in U. Applying (3.12), (3.13), (4.6), (4.7), and (4.8), we find

$$e_1b = (a-b)f$$
,  $e_2b = (c-b)h$ ,  
 $e_3b = (b-c)g$ ,  $e_ja = 0$ ,  $e_jc = -e_jb$ , (4.9)

$$\omega_1^2 = f\omega^2 + \frac{b - c}{b - a}\mu\omega^3, (4.10)$$

$$\omega_1^3 = \frac{b - c}{c - a} \mu \omega^2 + \frac{a - b}{c - a} f \omega^3,$$
 (4.11)

$$\omega_2^3 = -\mu \omega^1 + g \omega^2 + h \omega^3, \tag{4.12}$$

for j = 1, 2, 3. By applying (2.6), (4.9), (4.10), (4.11), and (4.12), we find

$$d\omega^{1} = \left(\frac{b-c}{a-b} + \frac{b-c}{c-a}\right)\mu\omega^{2} \wedge \omega^{3},$$

$$d\omega^{2} = f\omega^{1} \wedge \omega^{2} + \frac{a-c}{b-a}\mu\omega^{1} \wedge \omega^{3} + g\omega^{2} \wedge \omega^{3},$$

$$d\omega^{3} = \frac{a-b}{a-c}\mu\omega^{1} \wedge \omega^{2} - \frac{a-b}{a-c}f\omega^{1} \wedge \omega^{3} + h\omega^{2} \wedge \omega^{3}.$$

$$(4.13)$$

Using  $(\nabla_{e_2}e_1 - \nabla_{e_1}e_2 - [e_2, e_1])b = 0$ , we get

$$(a-b)e_2f + (b-c)e_1h = 2(c-a)fh + \frac{(b-a)(b-c)}{c-a}\mu g.$$
(4.14)

Similarly, from  $(\nabla_{e_3}e_1 - \nabla_{e_1}e_3 - [e_3, e_1])b = (\nabla_{e_3}e_2 - \nabla_{e_2}e_3 - [e_3, e_2])b = 0$ , we get

$$(a-b)e_{3}f + (c-b)e_{1}g = \frac{(a-c)(c-b)}{b-a}\mu h + \frac{2a(b+c)-b^{2}-c^{2}-2a^{2}}{c-a}fg,$$

$$e_{3}h + e_{2}g = \frac{c-b}{a-c}\mu f.$$

$$(4.15)$$

By computing  $d\omega_1^2$  and applying (4.10), (4.11), (4.12), (4.13), and Cartan's structure equations, we obtain

$$e_1 f = \frac{2(b-c)}{a-c} \mu^2 - f^2 - ab - \epsilon,$$
 (4.16)

$$e_1\left(\frac{b-c}{b-a}\mu\right) = \left\{\frac{b-c}{a-b} + \frac{2(a-b)}{a-c}\right\}\mu f,\tag{4.17}$$

$$e_{3}f + e_{2}\left(\frac{b-c}{a-b}\mu\right) = \frac{b+c-2a}{c-a} \left\{ fg - \frac{b-c}{a-b}\mu h \right\}. \tag{4.18}$$

Similarly, by computing  $d\omega_1^3$  and  $d\omega_2^3$ , and by applying (4.10), (4.11), (4.12), (4.13), and Cartan's structure equations, we obtain

$$e_1\left(\frac{b-c}{c-a}\mu\right) = \left\{\frac{2a^2 + 2c^2 + b^2 - ab - 3ac - bc}{(a-c)^2}\right\} \mu f,\tag{4.19}$$

$$e_1\left(\frac{a-b}{c-a}f\right) = -ac - \epsilon - \left(\frac{a-b}{c-a}\right)^2 f^2 + \frac{2(b-c)}{b-a}\mu^2,$$
 (4.20)

$$e_3\left(\frac{c-b}{c-a}\mu\right) + e_2\left(\frac{a-b}{c-a}f\right) = \frac{2a-b-c}{a-c}\left\{fh + \frac{b-c}{a-b}\mu g\right\},\tag{4.21}$$

$$e_2\mu + e_1g = \frac{a-b}{c-a}\mu h - fg,$$
 (4.22)

$$e_1h + e_3\mu = \frac{a-b}{a-c}fh + \frac{a-c}{a-b}\mu g,$$
 (4.23)

$$e_2h - e_3g = \frac{2(b-c)^2\mu^2}{(a-b)(a-c)} + \frac{a-b}{a-c}f^2 - g^2 - h^2 - bc - \epsilon.$$
 (4.24)

Combining (4.9), (4.16), and (4.20) yields

$$2(2a-b-c)(a-b)^{2} + 2(2a-b-c)(b-c)^{2}\mu^{2} + (a-b)(a-c)\{ab(a-b) + ac(a-c) + (2a-b-c)\epsilon\} = 0,$$
(4.25)

which is impossible unless  $\epsilon < 0$ , since we assume that  $a > b > c \ge 0$  in Case (i).

**CASE** (ii)  $(\delta = b(a+c) + 2\epsilon, c \le 0)$ . Since  $\delta$  is constant, we get  $b(a+c) = r_2 - 2\epsilon$  for some constant  $r_2$ . Combining this with (4.2) yields

$$b = c_3, a + c = c_4, (4.26)$$

for some constants  $c_3$  and  $c_4$ . For simplicity, let

$$\omega_3^1(e_2) = \tilde{\mu}, \qquad \omega_2^1(e_1) = \tilde{f}, \qquad \omega_1^3(e_1) = \tilde{g}, \qquad \omega_1^3(e_3) = \tilde{h}.$$
 (4.27)

If a and c are constant, then M is isoparametric. So, from now on, we may assume that a and c are nonconstant on U. Using (4.26), we get

$$e_i a = -e_i c, \quad j = 1, 2, 3.$$
 (4.28)

Thus, Lemma 3.2 yields

$$\omega_2^3(e_2) = \omega_2^1(e_2) = 0,$$
 (4.29)

$$e_1 a = (c - a)\tilde{h}, \qquad e_2 a = (b - a)\tilde{f}, \qquad e_3 a = (a - c)\tilde{g}.$$
 (4.30)

Equation (4.28) shows that the integral curves of  $e_2$  are geodesics in U. Applying (3.12), (3.13), (4.29), and (4.30), we find

$$\omega_1^2 = -\tilde{f}\omega^1 - \frac{a-c}{a-h}\tilde{\mu}\omega^3,\tag{4.31}$$

$$\omega_1^3 = \tilde{g}\omega^1 - \tilde{\mu}\omega^2 + \tilde{h}\omega^3, \tag{4.32}$$

$$\omega_2^3 = \frac{a-c}{c-b}\tilde{\mu}\omega^1 + \frac{a-b}{b-c}\tilde{f}\omega^3. \tag{4.33}$$

By applying (2.6), (4.31), (4.32), and (4.33), we find

$$d\omega^{1} = -\tilde{f}\omega^{1} \wedge \omega^{2} + \tilde{g}\omega^{1} \wedge \omega^{3} + \frac{b-c}{a-b}\tilde{\mu}\omega^{2} \wedge \omega^{3},$$

$$d\omega^{2} = -\left(\frac{a-c}{a-b} + \frac{a-c}{b-c}\right)\tilde{\mu}\omega^{1} \wedge \omega^{3},$$

$$d\omega^{3} = \frac{a-b}{b-c}\tilde{\mu}\omega^{1} \wedge \omega^{2} + \tilde{h}\omega^{1} \wedge \omega^{3} + \frac{a-b}{b-c}\tilde{f}\omega^{2} \wedge \omega^{3}.$$

$$(4.34)$$

Using  $(\nabla_{e_2}e_1 - \nabla_{e_1}e_2 - [e_2, e_1])a = 0$ , we find

$$(a-b)e_1\tilde{f} - (a-c)e_2\tilde{h} = 2(b-a)\tilde{f}\tilde{h} + \frac{(a-b)(a-c)}{b-c}\tilde{\mu}\tilde{g}.$$
 (4.35)

Similarly, from  $(\nabla_{e_3}e_1 - \nabla_{e_1}e_3 - [e_3, e_1])a = (\nabla_{e_3}e_2 - \nabla_{e_2}e_3 - [e_3, e_2])a = 0$ , we get

$$(a-b)e_{3}\tilde{f} + (a-c)e_{2}\tilde{g} = \frac{(a-c)(b-c)}{a-b}\tilde{\mu}\tilde{h} + \frac{2ab+2bc-2b^{2}-a^{2}-c^{2}}{b-c}\tilde{f}\tilde{g},$$

$$e_{3}\tilde{h} + e_{1}\tilde{g} = \frac{c-a}{b-c}\tilde{\mu}\tilde{f}.$$
(4.36)

By computing  $d\omega_1^2$  and applying (4.31), (4.32), and (4.33) and Cartan's structure equations, we obtain

$$e_2 \tilde{f} = \frac{2(a-c)}{b-c} \tilde{\mu}^2 - \tilde{f}^2 - ab - \epsilon,$$
 (4.37)

$$e_2\left(\frac{a-c}{a-b}\tilde{\mu}\right) = \left\{\frac{a-c}{b-a} - \frac{2(a-b)}{b-c}\right\}\tilde{\mu}\tilde{f},\tag{4.38}$$

$$e_3\tilde{f} + e_1\left(\frac{a-c}{b-a}\tilde{\mu}\right) = \frac{a+c-2b}{c-b}\left\{\tilde{f}\tilde{g} + \frac{a-c}{a-b}\tilde{\mu}\tilde{h}\right\}. \tag{4.39}$$

Similarly, by computing  $d\omega_1^3$ ,  $d\omega_2^3$ , and by applying (4.31), (4.32), and (4.33) and Cartan's structure equations, we obtain

$$e_2\left(\frac{a-c}{c-b}\tilde{\mu}\right) = \left\{\frac{2b^2 + 2c^2 + a^2 - ab - 3bc - ac}{(b-c)^2}\right\}\tilde{\mu}\tilde{f},\tag{4.40}$$

$$e_2\left(\frac{a-b}{b-c}\tilde{f}\right) = -bc - \epsilon - \left(\frac{a-b}{c-b}\right)^2 \tilde{f}^2 + \frac{2(a-c)}{a-b}\tilde{\mu}^2,\tag{4.41}$$

$$e_{3}\left(\frac{a-c}{b-c}\tilde{\mu}\right)+e_{1}\left(\frac{a-b}{b-c}\tilde{f}\right)=\frac{2b-a-c}{b-c}\left\{\tilde{f}\tilde{h}-\frac{a-c}{a-b}\tilde{\mu}\tilde{g}\right\},\tag{4.42}$$

$$e_1\tilde{\mu} + e_2\tilde{g} = \frac{a-b}{b-c}\tilde{\mu}\tilde{h} - \tilde{f}\tilde{g}, \tag{4.43}$$

$$e_2\tilde{h} + e_3\tilde{\mu} = \frac{b-a}{b-c}\tilde{f}\tilde{h} - \frac{b-c}{a-b}\tilde{\mu}\tilde{g},\tag{4.44}$$

$$e_1 \tilde{h} - e_3 \tilde{g} = \frac{2(a-c)^2 \tilde{\mu}^2}{(b-a)(b-c)} - \frac{a-b}{b-c} \tilde{f}^2 - \tilde{g}^2 - \tilde{h}^2 - ac - \epsilon. \tag{4.45}$$

Applying (4.30), (4.37), and (4.41) yields

$$2(2b-a-c)(a-b)^{2}\tilde{f}^{2} + 2(2b-a-c)(a-c)^{2}\tilde{\mu}^{2} + (b-a)(b-c)\{ab(b-a) + bc(b-c) + (2b-a-c)\epsilon\} = 0.$$

$$(4.46)$$

Using (4.26), (4.30), and (4.38), we find

$$e_2\tilde{\mu} = \frac{2[(a-b)^2 + (b-c)^2]}{(a-c)(c-b)}\tilde{\mu}\tilde{f}.$$
 (4.47)

On the other hand, by differentiating (4.46) with respect to  $e_2$  and using (4.26), (4.30), and (4.37), we obtain

$$4(a+c-2b)(a-c)^{2}\tilde{\mu}(e_{2}\tilde{\mu})$$

$$=b(a-b)(3a^{3}-13a^{2}b+10ab^{2}+7a^{2}c-4abc-2b^{2}c-3ac^{2}+bc^{2}+c^{3})\tilde{f}$$

$$-8\frac{(a+c-2b)^{2}(a-b)(a-c)}{b-c}\tilde{\mu}^{2}\tilde{f}+8(a+c-2b)(a-b)^{2}\tilde{f}^{3}$$

$$-(a-b)(a+c-2b)(4b-3a-c)\epsilon\tilde{f}.$$
(4.48)

Replacing  $\tilde{f}^2$  in (4.48) by using (4.46) yields

$$4(a+c-2b)(a-c)^{2}\tilde{\mu}(e_{2}\tilde{\mu})$$

$$=3(a-b)(a-c)(a+c-2b)\tilde{\epsilon}\tilde{f}$$

$$+3b(a-b)(a-c)(a^{2}-3ab+2b^{2}+2ac-3bc+c^{2})\tilde{f}$$

$$-8\frac{(a+c-2b)(a-c)[(a-b)^{2}+(b-c)^{2}]}{b-c}\tilde{\mu}^{2}\tilde{f}.$$
(4.49)

Substituting (4.47) into (4.49) yields

$$\tilde{f}(a+c-2b)\{b(a+c-b)+\epsilon\} = 0. \tag{4.50}$$

**CASE** (ii-a) ( $\tilde{f} = 0$ ). In this case, (4.37) and (4.41) imply that

$$2(a-c)\mu^{2} = (ab+\epsilon)(b-c) = (bc+\epsilon)(a-b). \tag{4.51}$$

The equality in (4.51) yields

$$b(ab+bc-2ac) = (a+c-2b)\epsilon. \tag{4.52}$$

**CASE** (ii-a.1) ( $\tilde{f} = 0$ ,  $b \neq 0$ ). In this case, (4.26) and (4.52) imply that ac is constant. Hence, by (4.26), we know that both a and c are constant. Thus, M is isoparametric.

**CASE** (ii-a.2) ( $b = \tilde{f} = 0$ ,  $\epsilon = 1$ ). In this case, (4.52) reduces to a + c = 2b. So, M satisfies the equality case of inequality (1.2). Therefore, by applying [7, Theorem 2], we know that M is given by Theorem 1.2 (2).

**CASE** (ii-a.3) ( $b = \tilde{f} = \epsilon = 0$ ). In this case, (4.37) implies that  $\tilde{\mu} = 0$ . Thus, by (4.31) and (4.33), we obtain  $\omega_1^2 = \omega_2^3 = 0$ . On the other hand, from (4.29), we have  $\nabla_{e_2}e_2 = 0$ . Therefore,  $\mathfrak{D}_1 = \operatorname{Span}\{e_1,e_3\}$  and  $\mathfrak{D}_2 = \operatorname{Span}\{e_2\}$  are integrable distributions in M with totally geodesic leaves. Hence, M is locally the Riemannian product of a line and a Riemannian 2-manifold  $N^2$ . Moreover, because the second fundamental form h of M in  $\mathbb{E}^4$  satisfies  $h(\mathfrak{D}_1,\mathfrak{D}_2) = \{0\}$ , Moore's lemma [13] implies that M is an open portion of a hypercylindrical  $\mathbb{R} \times N^2 \subset \mathbb{E} \times \mathbb{E}^3 = \mathbb{E}^4$ . Furthermore, from the assumption on the shape operator of M in  $\mathbb{E}^4$ , we know that the mean curvature of N in  $\mathbb{E}^3$  is constant and the Gauss curvature of N is nonpositive. Thus, we obtain case (3) of Theorem 1.1.

**CASE** (ii-b) ( $\tilde{f} \neq 0$ , b = 0). In this case, (4.50) yields  $(a+c)\epsilon = 0$ .

If  $\epsilon = 1$ , then a + c = 0. Hence, M is a minimal hypersurface satisfying the equality case of inequality (1.2). Thus, by applying [7, Theorem 2], we obtain case (2) of Theorem 1.2.

If  $\epsilon = 0$ , then (4.46) implies that a + c - 2b = 0 due to b = 0 and  $a \neq b$ . Hence, M satisfies the equality case of inequality (1.2). Since M has CMC, [7, Theorem 1] implies that M is either an isoparametric hypersurface or a minimal hypersurface which satisfies the equality  $\delta = 0$ . Hence, we obtain either case (1) or case (2) of Theorem 1.1.

**CASE** (ii-c) ( $b \neq 0$ ,  $\tilde{f} \neq 0$ ). In this case, (4.50) yields

$$(a+c-2b)\{b(a+c-b)+\epsilon\} = 0. (4.53)$$

If a+c-2b=0 holds, then (4.46) implies that a(a-b)-c(b-c)=0 which is impossible, since  $a \ge 0$ ,  $c \le 0$ , and a > b > 0 by assumption. Therefore, we

must have

$$\epsilon = b(b - a - c). \tag{4.54}$$

From (4.54),  $\epsilon \ge 0$ , and b > 0, we get

$$b \ge a + c. \tag{4.55}$$

On the other hand, by substituting (4.54) into (4.46), we find

$$(a+c-2b)[(a-c)^2\tilde{\mu}^2+(a-b)^2\tilde{f}^2]=b(b-a)^2(b-c)^2. \tag{4.56}$$

In particular, we obtain a+c>2b. Combining this with (4.55) gives b<0 which is a contradiction. Thus, this case is impossible.

The converse follows from [7, Theorem 2] and from direct computation.

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